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Arithmetic Operation Division. Quotient and Remainder. Logical Structures and Calculation Schemes

A project for fast execution of operation division on signed integer numbers is presented. The final result of the synthesis is a complete and unique combinational scheme. Synthesis requires a presentation of the theoretical ground for operation division and the resulting algorithms for calculating the quotient and the remainder. The operands and the results of the operation are twos' complement numbers. The first part of the article presents the synthesis of the logical structure and of the combinational scheme for calculation of the first result - the quotient. The second part presents the synthesized algorithm and the logic scheme for calculating the second result - the remainder. The entire logic scheme for performing a division operation described in the conclusion shows that this operation is executable over the switching time of the combinational scheme. Thus, the calculation of the two results is as fast as possible, which can be achieved. A further exemplary logical structure of the divider with a micro-pipeline organization is also presented. It is suitable for serial execution of operation division. The functionality of the presented here hardware divider is illustrated by numerical examples.

Key Words: Operation Division, Integer Numbers, Quotient, Remainder, Algorithm, Logic Scheme
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Main Considerations

In both scientific publications and academic monographs (the vast list of which we do not apply here), the theoretical as well as the algorithmic side of the operation division are mainly concentrated on the calculation of the first result - the quotient. There is also a second result of this operation - a remainder. The calculation of the quotient is sought by two main approaches: based on the definition of the operation ($Z=X/Y$) [1], [4] or the definition ($Z=(1/Y).X$). In most cases the synthesized algorithms are based on positive operands or non-signed operands [2], [3], [6], which operation is defined as division by module. Although digital arithmetic is a scientific area that has been explored for decades [1], [4] there are rarely publications that contain algorithms for determining the remainder. Operation division can also be defined by multiplication operation $X=Y.Z+R$, where R is the remainder. The conclusion of this definition is that the remainder is an integer and, in order for equality to be true, it should have the sign of the dividend X. The same n-bit format of the bit-set is considered for the operands and the results.

Operation division ($Z=X/Y$) is relatively rarely met (about 2.5%). Due to its complex algorithm, it is considerably slower than other integer number operations, which is recognized even now [10]. For these reasons, multi-step sequential devices are still being designed for its implementation [5]. However, this trend is an experience, so the efforts to end it are fully justified [6]. The desire for guaranteed speeding-up the calculations also leads us to a choice of a hardware implementation.

A consideration should also be given to the fact that the integer numbers are stored in the memory of the computer systems as 2's complement signed numbers. In this representation, they are operands, and the results are automatically obtained as 2's complement numbers too. This also applies to operation division. The use of the one's complement operands, which holds most authors to algorithms by module, is not up to date. The example of the non-homogeneous hardware solution shown in [6], which necessitates the alternation of adders and subtractors is a typical one. The main disadvantage of the subtractors is their greater cost compared to the adders. We try to avoid this drawback. It is also a fact that the machine commands for division in the digital processors require the calculation of both results (quotient and remainder), presented as twos' complement numbers regardless of the user's wishes. The two numbers remain at its disposal in two different ALU registers.

For illustration, in our project, we have chosen the non-restoring algorithm for twos' complement signed numbers based on the fixed divisor scheme. However, the approach we use can be successfully applied to other algorithms, such as those that allow the simultaneous obtaining of several digits of the quotient [4]. It is shown that the synthesized hardware divider calculates the quotient for both integer and fractional numbers, which is a prerequisite in dividing numbers represented in floating-point form.

Part 1 – Calculation of the Quotient

The logic synthesis presented here deliberately misses the detailed presentation of the chosen

algorithm, as it is a fundamental one in digital arithmetic. We recall that the direct calculation of the quotient Z begins after the left normalization of the dividend X and the divisor Y . Left-normalized operands are denoted here by names W_x and W_y . At each iteration of the algorithm, one digit (0 or 1) of the quotient z_m , $m = 1, 2, 3, \dots, n$ is obtained and the next operation (addition or subtraction) is determined. The rules are presented in Table 1.1.

Table 1.1. Determining the consecutive digit of the quotient and the next operation

Sign of the Remainder R_m	Sign of the Divisor W_y	Consecutive digit of the Quotient z_m	Next operation $R_{m+1} =$
+	+	1	$2.R_m - W_y$
+	-	0	$2.R_m + W_y$
-	+	0	$2.R_m + W_y$
-	-	1	$2.R_m - W_y$

As with multiplication, the idea of speeding-up operation division consists in the use of multiple adders. Thus the implementation of the actual division will be sought in the form of a combinational scheme.

The next digit z_m of the quotient is determined comparing the sign of the divisor with the sign of the current partial remainder R_m . Accepting Table 1.1 as a truth table, we can synthesize a logic function that determines the value of the next digit in the quotient. Its equation is as follows

$$z_m = (R_{m[n-1]} \cap W_y[n-1]) \cup \cup (R_{m[n-1]} \cap \overline{W_y[n-1]}), \quad m = \overline{0, n-2} \quad (1.1)$$

This is the elementary logical function of equivalence, i.e. if the signs of the current partial remainder and the divisor coincide, one (1) is recorded in the quotient, otherwise - zero (0). Along with this, a left shift is made to the partial remainder ($2.R_m$). The left shifting restores the order of the polynomial of the partial remainder to $(n-2)$.

The next partial remainder R_{m+1} is obtained after adding or subtracting the normalized divisor as indicated in the right column of Table 1.1 ($R_{m+1} = 2.R_m \pm W_y$). The arithmetic operation requires an adder. Function (1.1) is used for choosing the second operand in this sum.

So, we end this explanation stage with the resulting logical structure, presented in Figure 1.1.

As can be seen, the sign of the divisor $RGW_y[n-1]$ and the sign of the new partial remainder $R_{m[n-1]}$ form the current digit in the quotient z_m according to (1.1).

In order to obtain the current partial remainder R_m , the 1-bit left-shifted previous partial remainder R_{m-1} is fed at the left input of the current adder ADD_m , i.e.

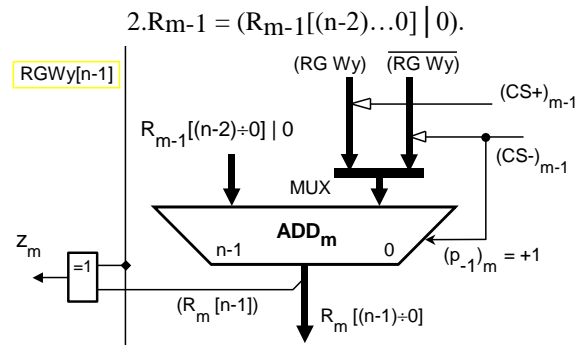


Fig. 1.1. Logical structure of the current adder in the divisor (current m level)

At the right input of the adder, the normalized divisor W_y is fed to the addition or subtraction via the two-input multiplexer MUX. It is the content of the RGW_y register where it remains until the end of the operation. The control of the right input of the adder is made by control signals $(CS+)$ and $(CS-)$. The logical values of these signals are encoded according to the following logic function:

$$\text{if } z_m = \begin{cases} 0, & \text{then } (CS+) = 1, (CS-) = 0; \\ 1, & \text{then } (CS-) = 1, (CS+) = 0. \end{cases} \quad (1.2)$$

The quotient is a signed number and it is automatically received as a twos' complement number. Its numerical part takes a bit-set of $(n-1)$ bits. Hence, the hardware divider must have $(n-1)$ number of levels to calculate $(n-1)$ digits. The sign of the quotient is determined in advance. It defines the initial content of the quotient registry RGZ .

$$\begin{cases} \text{if Sign}Z = 0, \\ \text{then } RGZ := 000\dots000 = 0; \\ \text{if Sign}Z = 1, \\ \text{then } RGZ := 111\dots111 = 2^{n-1} - 1. \end{cases} \quad (1.3)$$

The latter which needs to be clarified, is that the quotient does not always get exactly in this algorithm due to the asymmetry of the twos' complement representation of the operands. The rules used for quotient correction (adjustment) are presented in Table 1.2.

Table 1.2. Correction of the quotient

Sign of the Dividend X	Sign of the Divisor Y	Correction
+	+	No correction
+	-	+1
-	+	+1, if $R_{k-1+1} \neq 0$
-	-	+1, if $R_{k-1+1} = 0$

In this table, R_{k-1+1} denotes the last partial remainder, where k is the order of the polynomial of the dividend X , and l - the order of the divisor Y ,

respectively. Operands and results have the same format of n bits. The result of the left normalization of the operands gives also the number N (N=k-l+1), which presents the number of unknown digits of the quotient.

As shown in Table 1.2, when the quotient is not correct, it is adjusted by adding one to its least significant bit. This necessitates recognition of the relevant situations defined in the table. Recognizing (or decoding) the need for correction performs a logical function that depends on the signs of the operands, and in the latter two cases, whether or not the division is exact. If Table 1.2 is treated as a truth table, it can be considered that the logical function expressing the need for quotient correction is a disjunction of three logical terms

$$COR = cor1 \cup cor2 \cup cor3 , \quad (1.4)$$

where cor means correction. The first term expresses the correction condition according to the second row of the table

$$cor1 = \overline{(X[n-1]) \cap (Y[n-1])} . \quad (1.5)$$

The second and the third term (cor2 and cor3) are correction functions related to the third and fourth case respectively. These functions depend on the signs of the operands, as well as on the value of the last partial remainder, i.e. whether the division is exact or not. So we get the following expressions for them:

$$cor2 = [(X[n-1]) \cap \overline{(Y[n-1])}] \cap \overline{EQ(R)} , \quad (1.6)$$

and therefore

$$cor3 = [(X[n-1]) \cap (Y[n-1])] \cap EQ(R) . \quad (1.7)$$

In the above expressions EQ(R) denotes the logical value of a function that decodes a zero partial remainder in an arbitrary iteration (arbitrary level) during the division. Since this fact has to be decoded at each iteration, this function should have the following cumulative look:

$$EQ(R) = \bigcup_{m=0}^{n-2} EQ(R_m) . \quad (1.8)$$

In other words, function (1.8) expresses the possibility of prematurely exact division, which can be observed at each iteration.

We want to draw attention to the fact that, according to the understanding of the traditional division algorithm, the last partial remainder has an extremely complex definition of being the last one. For example, it is the last one if all the unknown digits of the quotient, i.e. if all N digits are obtained. However, there are cases of an exact premature division, after a different number of levels, before the control number is reached. In the sense of the problem solved here, i.e. in the sense of the hardware implementation of the division process, determining the remainder as the last one is extremely inconvenient as it can be obtained at any arbitrary level of the logic scheme of the divider. Therefore, the statement that the division is exact, if the quotient does not have a fractional part, is a very

convenient interpretation of whether or not a correction is needed in the last two cases of the table.

Based on the above explanation, we can present the synthesized part of the structure of the hardware divider.

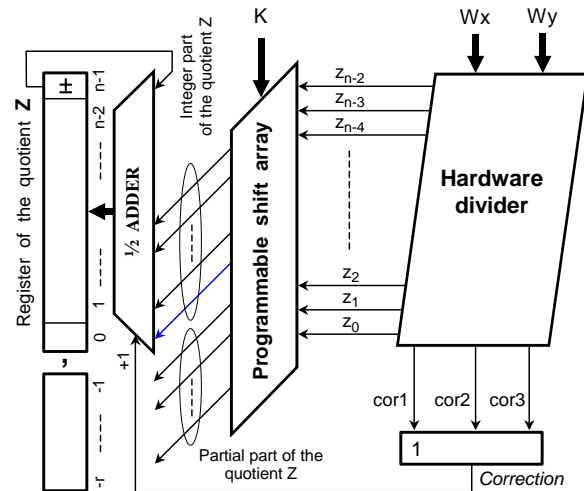


Fig. 1.2. Structural scheme for the stage of the actual division

The two left normalized operand which signs define the initial content of the quotient register RGZ are fed to the inputs of the hardware divider. (n-1) digits of the quotient (z_{n-2}, z_{n-3}, ..., z_1, z_0), as well as the three terms of the correction function (cor1, cor2, cor3), come out of the scheme. The quotient is fed to a right-shift programmable array. The shifting is in the direction of the radix point and it is an arithmetic shift, i.e. with the so-called sign extension. As can be seen from the drawing, this scheme is programmed to shift by parameter K. The number of shifts is defined as:

$$K = (n-1) - N . \quad (1.9)$$

The value of parameter K can be calculated at the left normalization stage when calculating the value of N (number of unknown digits in the quotient). Then, this value must be stored in a different registry RGK until the end of the operation.

As far as the correction is concerned, the above scheme illustrates how the result, which is shifted and positioned according to the right position of the radix point is adding with the value of the COR (0 or 1) function fed to the least significant bit №0 of the half-adder 1/2ADDER. The fractional part of the quotient in the structural scheme is shown for illustration only. It is untrue without correction and should be discarded. If we still want to keep it, then the correction (+1) must be applied not in the least significant bit of the integer (b_0), but in the least significant fixed bit of the real quotient (b_r).

Figure 1.3. below presents the synthesized logical scheme of a hardware divider, which always calculates 7 most significant digits of the quotient (z_6 to z_0).

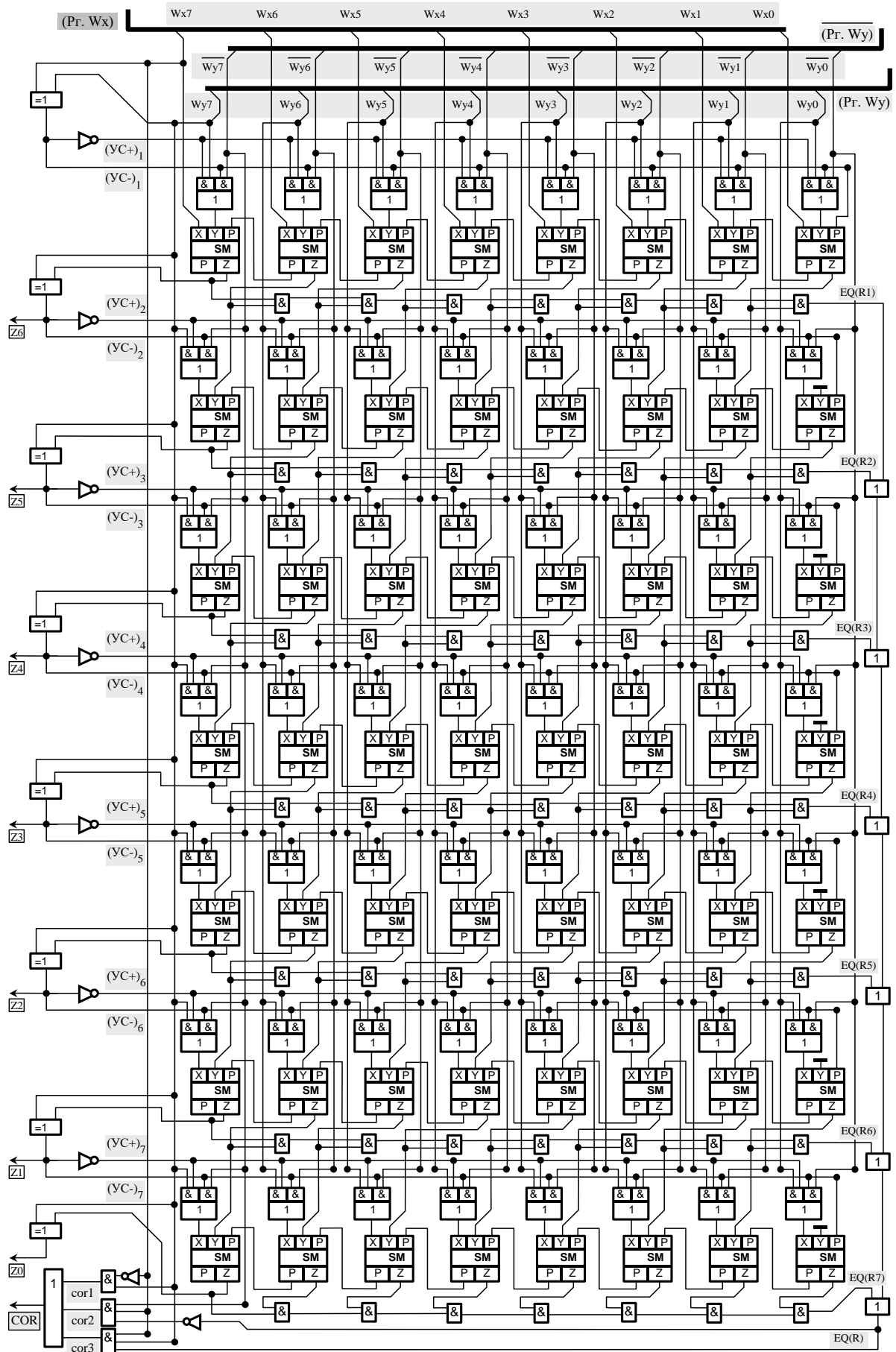


Fig. 1.3. Principal logic scheme of a hardware divider 8x8

After shifting of K -bits to the right, as shown in the examples and in the logical structure presented in Figure 1.2, the most significant N digits of the integer remain in the register of the quotient. As is known, the left-most bit contains the determined initial sign of the quotient z_7 , and the subsequent digits repeat it, completing at left the shifted N -bit quotient according to the rule for the sign extension.

As noted in the analysis, it is not possible for the hardware solution of the actual division to achieve that dynamics that is inherent in the algorithm. We mean the actual length of the quotient, which varies and it is expressed by the parameter N . The actual length of the quotient is adapted to the scheme by the parameter K , which initializes the programmable shift array. However, the functionality of the solution favors its use in the case of floating point division. As is known, the mantissas of the operands are always left normalized numbers, from which it follows that the quotient always gets the same length. In other words, when divide numbers with a left-fixed point, the hardware divider does not depend in its synthesis on the parameter N and its structure does not require a programmable shift array. In order to align the two cases, the shift array can be further manipulated to be transparent when divide left-fixed point numbers.

Part 2 – Calculation of the Remainder

Theoretical Ground

Based on the synthesis outlined above in the first part, here we present its continuation, referring to the hardware calculation of the second result - the remainder. In conclusion, we describe our idea of the complete structure of the combinational logic scheme of the divider, which makes the division operation identical to the multiplication operation in both structure and performance. In order to optimize the combinational scheme of the divider and minimize its latency, the same methods that are possible on the hardware multiplier [4] can be used.

We have already pointed out that division $Z=X/Y$ is the most complex arithmetic operation, unlike any other and generates two independent results required in the computational algorithms - quotient Z and remainder R . The following definition of operation division can be given: the quotient and the remainder are such numbers that $Z.Y+R = X$.

We also recall that Y is called a module for comparing number X with other numbers having the same remainder R as well as that the quotient Z is defined as a multiplication factor of the module Y in this conception. Exactly in this interpretation, number X can be expressed by the multiplication factor Z , the comparison module Y and the remainder, or the image R , so $X = Z.Y + R$.

The iterative algorithm which is applied to obtain the digits of the quotient is preceded with a left normalization of the operands. In the process of this normalization, the integer N , indicating the number of unknown digits of the quotient, is determined. The number N is defined by the equation $N = k-l+1$.

Presenting the algorithm in [4], it is shown that the partial remainder, which determines the last digit in the quotient, can be used to derive the following equation

$$2^{-(k-1)}.R_{k-l+1} = X - Z.Y \quad .$$

According to the definition given at the beginning, this equality can be written as

$$2^{-(k-1)}.R_{k-l+1} = R \quad . \quad (2.1)$$

Equality (2.1) is remarkable in that it expresses how the second result of a division operation can be obtained, namely the remainder R of the division. The conclusion is that the remainder R is contained in the last partial remainder R_{k-l+1} , which should be shifted $(k-1)$ -bit to the right to be represented correctly as an integer. This is a signed number and will be automatically received in its twos' complement representation.

There is one further explanation. If the last subtraction yielding the last partial remainder R_{k-l+1} , has been successful, it contains the desired remainder R . However, if the subtraction has been unsuccessful, then the last partial remainder R_{k-l+1} should be restored from the preceding partial remainder R_{k-l} . The desired remainder R is to be contained in R_{k-l} . Restoration of the previous partial remainder is achieved by adding or subtracting the divisor Wy , an operation selected according to the rule as follows

$$\left\{ \begin{array}{l} \text{if } (R_{k-l+1}[n-1]) = Wy[n-1], \\ \quad \text{then } R_{k-l} = R_{k-l+1} - Wy; \\ \text{if } (R_{k-l+1}[n-1]) \neq Wy[n-1], \\ \quad \text{then } R_{k-l} = R_{k-l+1} + Wy. \end{array} \right. \quad (2.2)$$

Finally, the remainder R can be calculated applying the following algorithm:

- If the obtained quotient Z is an odd number, the remainder R is contained in the last difference.
- If the obtained quotient Z is an even number, the remainder R is contained in the preceding difference. In this case, for the determination of the remainder, it is necessary to restore the previous difference.
- The final remainder is obtained after an arithmetic shift to the right of the $(k-1)$ bits of the corresponding partial remainder.

Two numerical examples illustrating the explained algorithm are presented below. Both examples illustrate an inexact division, i.e. division with remainder. The first example illustrates a division of two positive integers and the quotient being an even number. The latter fact leads the algorithm to the case when the remainder is contained in the preceding difference (000100). It is restored, then $(k-1)$ -bit shifting to the right follows and the remainder is formed.

Examples

Example 1. Perform a division operation $Z=X/Y$ of the numbers $X=31$ and $Y=5$, which are presented in a bitset of 6 bits ($n = 6 [b]$).

We should get the following results: quotient $Z=6$ and remainder $R=1$, i.e. $31=5.6+1$.

$$|X| = 0\ 11111 ; \quad |Y| = 0\ 00101 .$$

Normalization of the operands X and Y.

$$\begin{array}{r|l} 0 & 11111 = X \\ \hline 0 & 11111 = W_x \end{array} \quad \begin{array}{l} \text{Dividend is normalized} \end{array}$$

$$\begin{array}{r|l} 0 & 00101 = Y \\ \hline 0 & 10100 = W_y \end{array} \quad \begin{array}{l} \text{Left normalization of} \\ \text{the Divisor (2 bits)} \end{array}$$

$$N = 2-0+1 = 3 \text{ (3 unknown digits of the quotient)}$$

$$k-1 = 2-0 = 2 \text{ - shifted to } 2[b] \text{ to form the remainder.}$$

$ Z = 0\ 00zzz = ?$	$W_y = 0\ 10100$
$0\ 00110, = 6.$	$W_x = 0\ 11111$
subtraction +	1 01100
Diff. > 0	0 01011 ←
subtraction +	0 10110
Diff. > 0	1 01100 ←
subtraction +	0 00010 ←
Diff. < 0	0 00100 ←
subtraction +	1 01100
Diff. < 0	1 10000 ←
Recovery of the previous partial remainder:	
addition +	1 10000
subtraction +	0 10100
subtraction +	0 00100
$k-1=2 \rightarrow$	0 00001, ←

R = 1 .

In this case, the quotient does not need a correction: $Z=+6$.

The second example illustrates the division of two negative numbers, and the quotient is being an odd number. The latter fact leads the algorithm to the case when the remainder is contained in the last difference (10100000). This is the case where the last difference contains the remainder that is formed after the required shifting.

Example 2. Perform a division operation $Z=X/Y$ of the numbers $X= -97$ and $Y= -7$, which are presented as twos' complement numbers in a bitset of 8 bits ($n=8[b]$). We should get this answer: quotient $Z=+13$ and remainder $R= -6$, i.e. $(-97) = (-7).13-6$.

$$[X]_{2'sC} = 1\ 0011111 ; \quad [Y]_{2'sC} = 1\ 1111001 .$$

Normalization of the operands X and Y.

$$\begin{array}{r|l} 1 & 0011111 = X \\ \hline 1 & 0011111 = W_x \\ \hline 1 & 1111001 = Y \\ \hline 1 & 0010000 = W_y \end{array} \quad \begin{array}{l} \text{Dividend is normalized} \\ \text{Left normalization of} \\ \text{the Divisor (4 bits)} \end{array}$$

$$N = 4-0+1 = 5 \text{ (5 unknown digits of the quotient)}$$

$$k-1 = 4-0 = 4 \text{ - shifted to } 4 [b] \text{ to form the remainder.}$$

$[Z]_{2'C} = 0\ 00zzzz = ?$	$W_y = 1\ 0010000$
$0\ 0001101, = 13$	$W_x = 1\ 0011111$
subtraction +	0 1110000
1 ≠ 0 Sign(Wy) ≠ Sign(Diff)	0 0001111 ←
addition +	0 0011110 ←
1 = 1	1 0010000 ←
subtraction +	1 0101110 ←
1 = 1	0 1011100 ←
subtraction +	0 1110000 ←
1 = 1	1 1001100 ←
subtraction +	1 0011000 ←
1 ≠ 0	0 1110000 ←
addition +	0 0001000 ←
1 = 1	1 0010000 ←
subtraction +	1 0100000 ←
$k-1=4 \rightarrow$	1 1111010, ←

= [R]_{2'C}; R = -6 .

In this case, the quotient does not need an adjustment: $Z=+13$.

Operation division is the most complex of all operations on integer numbers. Various situations in various combinations can occur during their execution. Such situations are indefiniteness ($Y=0$), overflow, exact division, and prematurely exact division. To illustrate all these cases, a number of numerical examples should be performed. Such examples, which are useful for real synthesis, can be seen in [8].

Synthesis of the Logical Structure

The exposed theoretical grounds, algorithms and numerical examples allow us to synthesize that part of

a logical structure that complements the one presented in the first part of the explanation to its final appearance.

We consider the presentation of our project to be completed with what we have said here. There are, of course, a few more details, such as the case of undefined operation (when $Y=0$), or the case of overflow when divide integer numbers, etc. The reflection of these subtleties in the synthesized scheme is quite possible, requiring only an excellent knowledge of the algorithm.

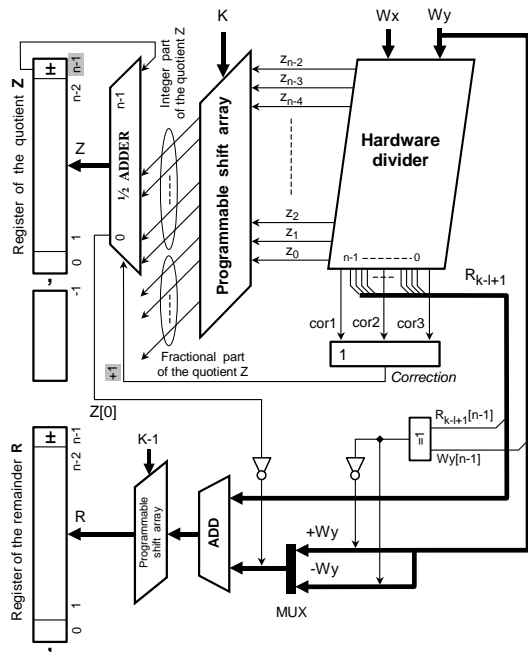


Fig. 2.1. Logical structure of the hardware divider, supplemented by the elements needed to calculate the remainder

The complete implementation of the hardware divider in the form of a single combinational scheme is entirely possible. This translates the division into a single cycle operation, making it analogous to multiplication operation, as well as to some structural elements in the Floating Point Units (FPU).

Conclusion

We briefly describe the entire composition of this sophisticated combinational circuit. Only 4 registers are needed - 2 input registers for the input operands X and Y and two output registers for both results - quotient Z and remainder R. Between these two pairs of registers, the following composite combinational circuits are sequentially arranged. First of all, on the input registers, there are schemes for determining the number of the leftmost insignificant digits of the operands. These are combinational schemes that are synthesized in our project, published in [7].

The numbers formed by these two schemes are fed to an adder that calculates the above mentioned number N. As a result of this adder, there may be also the numbers K and (K-1) required to initialize the next functional elements of the scheme. The operands are still at the input of the hardware divider, and two

combinations come at its outputs. The first one, passing through the shift array and the half-adder 1/2 ADDER (Figure 1.1), is loaded in the register RGZ as a first result - quotient Z. The second one, representing the last difference R_{n-1} , passes sequentially through the adder ADD and the right shifting array and is loaded in the output register RGR as a second result - remainder R. If the scheme is used to divide floating-point numbers, the remainder loses its meaning and the number K takes a value of 0 that makes the shifting array transparent.

The two numerical examples presented in the article illustrate the functioning of the algorithm and the synthesized logical structure. More numerical examples can be seen in [8].

The sequential elements in the described combinational scheme can be organized into a micro-pipeline shown in Figure 2.2. The pipeline organization will allow to increase the performance of the calculation unit in cases where the mathematical calculations contain multiple consecutive division operations. The micro-pipeline control of the hardware divider can be achieved with the methods and means, which are described in details in the monograph [9].

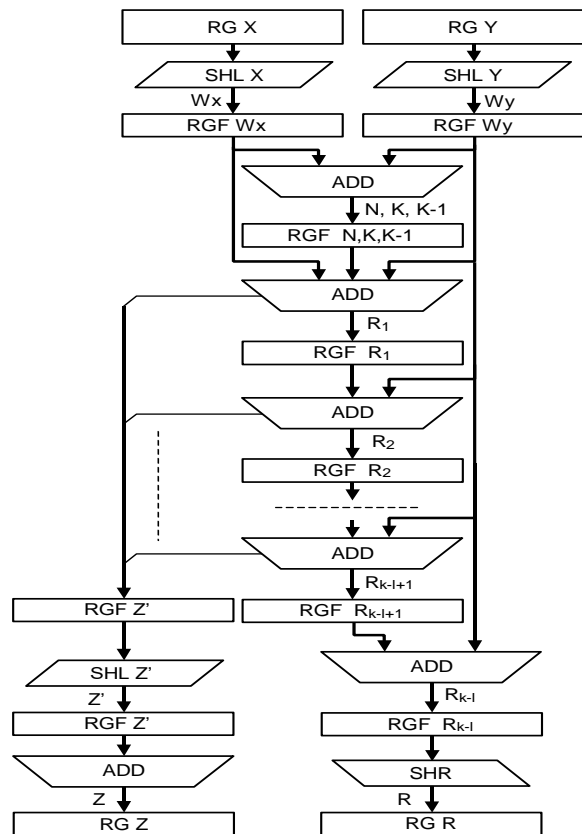


Fig. 2.2. Exemplary logical structure for micro-pipeline organization of the hardware divider

As can be seen from the structure of the pipeline, it includes RGF registers, combinational schemes – adders ADD, programmable arrays shifting to the left – SHL, and right – SHR. The structure also includes finite state machines required to control the individual stages of the pipeline, which are depicted on the diagram.

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АРИФМЕТИЧЕСКОЕ ДЕЛЕНИЕ. ЧАСТНОЕ И ОСТАТОК. ЛОГИЧЕСКИЕ СТРУКТУРЫ И ОПЕРАЦИОННЫЕ СХЕМЫ

Представлен проект вычислителя для быстрого выполнения операции деления целых чисел со знаком. Конечным результатом синтеза является полная и уникальная комбинационная схема. Операнды и результаты операции являются числами, представленными в дополнительном коде. Приведены синтез логической структуры и комбинированной схемы для расчета первого результата – частного и синтезированный алгоритм и логическая схема для вычисления второго результата - остатка. Операция выполняется в течение времени переключения схемы комбинации, то есть вычисление двух результатов происходит максимально быстро.

Ключевые слова: операция деление, частное, остаток, алгоритм, логическая схема.**Д. С. ТЯНЕВ, Ю.П. ПЕТКОВА**

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АРИФМЕТИЧНЕ ДІЛЕННЯ. ЧАСТКА І ЗАЛИШОК. ЛОГІЧНІ СТРУКТУРИ І ОПЕРАЦІЙНІ СХЕМИ

Представлений проект обчислювача для швидкого виконання операції ділення цілих чисел зі знаком. Кінцевим результатом синтезу є повна і унікальна комбінаційна схема. Синтез вимагав представлення теоретичного обґрунтування для операції ділення і отриманих алгоритмів для обчислення частки і залишку. Операнди і результати операції є числами, представленими в додатковому коді. У статті наведено синтез логічної структури і комбінованої схеми для розрахунку першого результату – частки, а також синтезований алгоритм і логічну схему для обчислення другого результату – залишку. Операція виконується протягом часу перемикання комбінаційної схеми, таким чином, обчислення двох результатів відбувається максимально швидко.

Ключові слова: операція ділення, частка, залишок, алгоритм, логічна схема.